Article

Commonality in structure among food web networks

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Abstract

A goal of this study was to determine similarities in structure among food webs that are otherwise disparate with regard to species, population, and size. Food webs were examined as directed, unweighted graphs in order to normalize food webs with regard to biomass and population/species distinctions. The graphs were further normalized with regard to topological size and existence of circuits through the reduction of each strongly connected component to a single node. This had the added benefit of resulting in networks with more clear delineation between trophic levels. Finally, common induced subgraphs were considered for their obvious value in characterizing network structure. Through this study we determined not only that there are pairs of systems that are highly similar in structure once appropriately normalized for size, makeup, and geographical location, but also that a majority of food webs have similar structural components when compared with random food webs.

Keywords network ecology; graph theory; food webs; directed graphs.

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1 Introduction

Ecosystems are complex. Management of ecosystems for environmental and societal goods and services can be even more complex. Finding commonalities and patterns in this complexity will help streamline management efforts. The complexity in ecosystems can be captured in its food web which describes predator prey relationships and flow of energy between species.

Food webs are one type of network that has been subject to examination through the founding disciplines of network ecology and graph theory. Dunne (2002, 2004, 2009) has done much work characterizing network structure of food webs demonstrating the role of connectedness, size, and robustness. Food webs, like most real world networks, are not random (Williams and Martinez, 2000). Food webs from different types of ecosystems share fundamental structural and ordering characteristics (Dunne et al., 2004).

Finding ways to describe and quantify these fundamental structural and ordering characteristics can be challenging due to the complexity of the food webs. Several metrics and techniques have already been developed in the field of network ecology. Here we attempt to advance this field by proposing a methodology for examining commonality among food web models that is strongly rooted in graph theory and builds from prior work of Allesina et al. (2005).

We focus on "wet" food webs, including marine, brackish, and freshwater systems from around the world and propose a set of metrics derived from graph theory that can be used to evaluate similarities and differences across these complex systems. Using a combined graph theory and network ecology approach, we first establish that, like other real-world networks, food webs have more organization than randomly generated webs (Watts and Strogatz, 1998; Williams and Martinez, 2000). We then test for similarities and differences across all food web types to examine whether there are mathematical properties of food webs that are ubiquitous around the world.

Our approach is advancement over other studies because of our large sample size (21) and ecosystem diversity (i.e. fresh-water, estuarine, marine). Many other comparative studies of food webs only look at 3-5 networks and are typically all a similar type of ecosystem (Allesina et al., 2005; Bascompte and Melián, 2005; Dunne et al., 2004). We also examined larger subgraph structures (up to 7 nodes) compared to other studies (3 nodes) (Borrelli, 2015).

2 Method

We will use the following terminology throughout this manuscript.

Definition: A directed graph (henceforth referred to as a graph) is an ordered pair of sets (V, E) of vertices (or *nodes*) V and edges E. Each edge e in E is itself an ordered pair (u, v) of distinct elements from V, (i.e. we do not allow loops or multiple edges, but circuits of length 2 are permitted). The <u>in-degree</u> (alternatively <u>out-degree</u>) of a node v in a graph G is the number of edges in G of the form (x, v) (alternatively (v, x)) for any vertex x in G.

Definition: A graph *G* is <u>connected</u> if, for every pair u, v of vertices in *G*, there is a set of edges in *G* (e_1 , e_2, \ldots, e_n) such that u is in e_1 , v is in e_n , and for each i the edges e_i and e_{i+1} have a non-empty intersection.

Definition: An <u>*n*-path</u> is a connected graph on *n* vertices in which one vertex has out-degree 1 and in-degree 0 (the *source*), one vertex has out-degree 0 and in-degree 1 (the *sink*), and the remaining vertices each have indegree and out-degree 1. An <u>*n*-circuit</u> is a connected graph on *n* vertices in which each vertex has both indegree and out-degree 1. A graph that contains no circuit is acyclic.

Definition: A graph $G = (V_G, E_G)$ is an <u>induced subgraph</u> of a graph $H = (V_H, E_H)$ if there is an injective function *f* from V_G to V_H such that for any edge (u, v) in E_G the corresponding edge (f(u), f(v)) is in E_H , and if (u, v) is not an edge in E_G then (f(u), f(v)) is not an edge in E_H .

As an example, the 4-path is not an induced subgraph of the 4-circuit, but it is an induced subgraph of the *n*-circuit for all n > 4.

Definition: The <u>order</u> of a graph *G* is the number of vertices in *G*, denoted n(G). Its <u>size</u> e(G) is the number of edges in *G*.

2.1 Food web networks

Our goal with this project was to determine commonality among food web structures, in particular simplified, acyclic models of food webs irrespective of geographic location, size, and species particulars. We began with 21 food webs (*FW*) imported from Ecopath (www.ecopath.org) to Sagemath (www.sagemath.org) as graphs based on the diet matrix (Table 1). The Ecopath diet matrix captures the percent of diet of prey items for every

predator in the food web. Each Ecopath food web was created by different researchers for different purposes and therefore has unique classifications and groupings of species (Table 2). To standardize these diverse models, each food web was given two treatments prior to any analysis: (1) removal of detritus and (2) removal of circuits.

Table 1 Networks used in analysis. Networks published prior to 2010 were downloaded from the Ecopath website (www.ecopath. org). All networks were assigned both a three letter abbreviation (Abbr.) and a number (Num.) that is used in subsequent tables and figures.

Name	Abbr.	Num.	Reference
Aleutian Islands, Alaska, USA	ALE	1	(Guenette and Christensen, 2005;
			Guenette et al., 2007)
Weddell Sea, Antarctica	WED	2	(Jarre-teichmann et al., 1997)
Lake Tanganyika, Burundi	TAN	3	(Moreau et al., 1993b)
Lake Ontario, Canada	ONT	4	(Halfon and Schito, 1993)
Northern Gulf of St. Lawrence, Canada	GSL	5	(Morissette et al., 2003)
Lake Aydat, France	AYD	6	(Reyes-Marchant et al., 1993)
Great Barrier Reef, Australia	GBR	7	(Gribble, 2005)
Gironde Estuary, France	GIR	8	(Lobry, 2004)
Iceland	ICE	9	(Buchary, 2001)
Lake Kinneret, Israel	KIN	10	(Walline et al., 1993)
Lake Victoria, Kenya	VIC	11	(Moreau et al., 1993a)
Narragansett Bay, Rhode Island, USA	NAR	12	(Byron et al., 2011a)
Laguna de Bay, Philippines	LDB	13	(Delos Reyes, 1995)
Lagoons, Rhode Island, USA	LRI	14	(Byron et al., 2011b)
Saco River Marsh, Maine, USA	SRM	15	Byron, unpublished
Southeast Alaska, USA	SAK	16	(Guenette et al., 2007)
PrakramaSamudra Reservoir, Sri Lanka	PRA	17	(Moreau et al., 2001)
Prince William Sound, Alaska, USA (pre oil spill)	PW1	18	(Dalsgaard and Pauly, 1997)
Prince William Sound, Alaska, USA (post oil spill)	PW2	19	(Okey and Pauly, 1999)
West Florida Shelf, USA	WFS	20	(Okey et al., 2004)
Lake Kariba, Zimbabwe	KAR	21	(Machena et al., 1992)

Table 2 Metadata describing the motivation for creating the food web model and the different emphasis on species groupings in each study system. See Table 1 for full ecosystem names associated with the first column, 'Abbr.'. 'Percent of FW nodes aggregated' is the number of species groups that contain multiple species divided by the total number of species groups in the original food web model, as defined by the author, 'FW nodes'. 'RAM nodes' is the number of nodes in the RAM after removing cyclicity and detritus.

Abbr.	Study Goal	Species Focus	FW nodes	Percent of FW nodes aggregated	RAM nodes
ALE	Evaluate whether predation by killer whales might explain the decline of Steller sea lions in the central and western Aleutian Islands.	Steller sea lion and their principal prey species	40	60%	34
WED	Integrate the results of the various research efforts directed towards the shelf communities into a coherent whole.	dominant groups of benthic shelf community	20	100%	15
TAN	Quantify the food web and the production of pelagic fish and invertebrates.	pelagic fish and invertebrates	7	100%	4
ONT	Characterize the food web.	Phytoplankton, zooplankton, benthos were aggregated. Fish, mysid, amphipod species were left independent.	14	29%	13
GSL	Impact of groundfish collapse.	phytoplankton and detritus to marine mammals and seabirds, including harvested species of pelagic, demersal,	32	59%	30

		and benthic domains			
AYD	Understand functioning of eutorophic	emphasis on two dominat fish species,	11	82%	10
	ecosystem.	perch (<i>Percafluviatilis</i>) and roach			
CDD		(Rutilusrutilus)	20	750/	0
GBK	in (1) mangrove (2) lagoon songroup	fish and prawn	32	/5%	8
	and (3) coral reef systems, and the				
	possible confounding effects of				
	independently developed fisheries				
	management plans.				
GIR	Improve understanding of the	estuarine fish	18	89%	17
	complexity of estuarine ecosystems and				
	response to various pressures.				
ICE	Describe North Atlantic marine	two primary producer groups, five	24	63%	20
	ecosystem with fisheries prior to	invertebrate groups, twelve fish groups			
	expansion of large-scale commercial	(including one juvenile group for cod),			
	fisheries.	one seabirds group, three marine			
WIN		mammals groups and one detritus group	1.4	710/	10
KIN	Characterize the food web.	Good data for biomass and production	14	/1%	13
		diet and catches of main fish species			
VIC	Evaluate change in dynamics of fish	fish-centric model	16	75%	12
VIC	community after introduction of Nile	IIsii-centric model	10	1370	12
	perch.				
NAR	Calculate carrying capacity for shellfish	Includes all trophic levels with	15	93%	14
	aquaculture.	emphasis on filter feeders.			
LDB	Text not available, only data tables	Text not available, only data tables	17	71%	15
LRI	Calculate carrying capacity for shellfish	Includes all trophic levels with	16	88%	15
	aquaculture.	emphasis on filter feeders.			
SRM	Characterize the food web.	fish and birds	29	62%	27
SAK	Understand why sea lions increased in	Steller sea lion and their principal	40	68%	19
	the presence of killer whales in	prey species			
DD A	Southeast Alaska.	commencial fisheries and introduced	17	710/	16
РКА	importance of unexploited fish stocks	tileniine fish	1/	/ 1 %0	10
PW1	Characterize trophic interactions prior to	not fish-centric plankton to mammals	10	95%	18
1 99 1	oil spill	not fish-centre, plankton to manimars	19	9570	10
PW2	Understand structure and functional	primary producers, zooplankton.	48	73%	13
	characteristics of food web after oil spill.	benthic invertebrates, planktivorous			
	1	'forage fishes', larger fishes, birds,			
		mammals, and detritus			
WFS	Community effects of seafloor shading	primary producers	59	92%	6
	by plankton blooms.				
KAR	Assess trophic interrelationships and	Trophic groups selected based on	10	70%	9
	community structure.	known importance and availability of			
		data from the literature. Some groups			
		minor importance for overall trophic			
		flows. Some fish species were grouped			
		both because commercial landing			
		statistics do not separate individuals			
		species and also because their biology			
		is similar.			

2.2 *RAM* generation process

Despite the unique species groupings in each web, there is one exception - detritus. Every Ecopath model must include a detritus (decaying organic matter) component. Detritus is used to capture any unused energy in the ecosystem and in that way is common across all webs. The vertex with this detritus label shares at least one edge with every other vertex in each food web. Because we are interested in examining similarities and differences across food webs, the detritus vertex was removed from every food web. What remains from FW is a graph F.

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It is common that food webs contain circuits whereby energy flows cyclically between specific predator and prey groups, typically across 2 adjacent trophic levels. Because we are interested in how energy moves across multiple trophic levels, smaller circuits such as these become less consequential. Cycles or hereafter, circuits, in F are located and reduced to a single vertex, resulting in a reduced acyclic model (*RAM*) of the food web (see Allesina et al. 2005 for another treatment of reduced acyclic graphs). The resulting 21 *RAMS* are more uniform in size than the graphs in *FW* and contain fewer vertices, leading to simpler computational analysis.

2.3 Random RAM generation process

Because one of our goals is to find properties of networks that are unique to food webs, random graphs were created for comparison. Each graph F in FW has a density d(F), the ratio of the number of edges to n(F)(n(F)+1). Note that n(F)(n(F)+1) is the maximum number of edges in a graph on n(F)+1 vertices. A random graph on n(F)+1 vertices was generated through inclusion of each potential edge among each pair of vertices with probability equal to d(F). The resulting graph is then stripped of a vertex of highest total degree (i.e. the sum of in-degree and out-degree). What results is a graph R_F with the same order as and similar density to F. The set of all graphs of the form R_F is denoted RFW. Each graph in RFW undergoes the RAM generation process, described above, to result in a random equivalent of each RAM, or an RRAM.

2.4 Induced subgraphs

There exist 243,262 graphs on up to 7 nodes that are acyclic and connected, which were placed into array A. Each graph in A was examined for inclusion in each RAMR as an induced subgraph, resulting in a binary array A_R . These binary arrays were subsequently added component-wise and the resulting array A_t , with integer components between zero and 21 inclusive, was generated. The array A_t is an indicator of occurrence for each graph in A among the RAMS. Graphs from A with at least five vertices were examined for high occurrence. Those that appeared often were included in a set which we will refer to as S, consisting of induced subgraphs of approximately two-thirds of the RAMS examined (Fig. 1). It was discovered that no graph in A with greater than 6 nodes is an induced subgraph of a significant number of RAMS. Connected, acyclic graphs with more than 6 nodes did not appear as induced subgraphs with high enough frequency to be studied. Next, each graph in S was examined for its inclusion in each RRAM.

2.5 Network metrics

To examine similarities and differences across food webs, individual metrics of each FW and *RAM* were calculated and standardized against the metrics of order or size. The eight metrics listed in Table 3 were used for cluster and principle component analyses. Each metric captures a unique quality of the networks useful for examining similarities and differences across ecosystems.

We define some relevant graph theoretic terms below

Definition: The <u>clique number</u> of a graph is the order of the largest complete subgraph. An undirected graph is <u>complete</u> if each vertex is adjacent to every other vertex.

Definition: The <u>connectivity</u> (alternatively <u>edge-connectivity</u>) of a graph is the fewest number of vertices (edges) the removal of which results in a disconnected graph.

Definition: A graph's <u>density</u> is the ratio of its size to the maximum possible number of edges among its vertices.

Definition: The <u>distance</u> between vertices u, v in a graph G is the length of the shortest path from u to v. The <u>diameter</u> of G is the length of the greatest distance. If there are vertices with no path between them then the <u>finite diameter</u> is defined to be the length of the greatest distance between vertices that do have a connecting path.

Definition: An independent set is a collection of vertices with no adjacencies among one other.

Definition: An <u>induced path</u> is simply an induced graph in the form of a path. That is, no vertex along the path is adjacent to any other besides its neighbors along the path.

Definition: The <u>eccentricity</u> of a vertex v is the greatest distance from v to any other vertex in a graph. The <u>radius</u> of a graph is the lowest eccentricity.



Fig. 1 The five six-node graphs below are those that appear in *14 RAMS* (Fig. 1a) and 13 *RAMS* (Figs. 1b-1e). None of the graphs in Fig. 1 appear as induced subgraphs in any of the *RRAMS*.

2.6 Cluster analysis

A cluster analysis was performed to examine relatedness among food webs. Clusters are based on the shortest Euclidean distances between computed metrics. The resulting dendrogram plot is of the hierarchical binary cluster tree where the height of the U-shaped bars are the distances (y-axis) between networks (x-axis) being connected.

2.7 PCA

A Principle Component Analysis (PCA) was performed to examine relationship between metrics. Since variances among metrics were similar due to standardizing against order or size, raw data was used to perform the PCA. The first principal component and second principal component were plotted for each network for both food webs and *RAMS*. A biplot of the principal component coefficients showing variables represented as vectors. This biplot allows visualization of the magnitude and sign of each variable's contribution to the first two principal components, and how each observation is represented in terms of those components.

3 Results

3.1 Induced subgraphs

No graph in *S* was found as an induced subgraph in any *RRAM*. It was determined that each *RRAM* is much smaller than the *RAMS*. Ecologically, the naturally-occurring *RAMS* have a more complex structure than randomized ones, and naturally-occurring food webs appear to have much lower cyclicity than randomized food webs.

Large graphs that were found to be induced subgraphs of a majority of *RAMS*, i.e. the graphs in *S*, were not represented in all *RAMS*. There are five systems in which no graph from *S* appeared as an induced subgraph (Lake Tanganyika in Burunidi, Lake Aydat in France, the Great Barrier Reef in Australia, West Florida Shelf in USA, Lake Kariba in Zimbabwe) (Table 3). The remaining 16 *RAMS* did contain at least one induced subgraph from the set *S*, and 9 of those *RAMS* contained all 5 common induced subgraphs (Aleutians in USA, Northern Gulf of St. Lawrence in Canada, Narragansett Bay in USA, Laguna de Bay in Philippines,

Rhode Island coastal lagoons in USA, Saco River estuary marsh in USA, Southeast Alaska, Lake Prakrama Samudra in Sri Lanka, and Prince William Sound Alaska prior to the oil spill) (Table 3). There appears to be no geographic or environmental pattern to the number of these common induced subgraphs a network contains (Fig. 2).

Table 3 Metrics computed for each Food Web (FW) and *RAM*. Metrics were standardized by order or edges making all values a relative proportion. The number of induced subgraphs for each network is specified in the first column, *Ind. Sub*. Networks either contained all 5 of the listed induced subgraphs (5), at least one induced subgraph (1+), or no induced subgraphs. Network names are listed in Table 1.

Ind. Network Sub. Num.		clique number/ order (undirected)		connectivity/ order (undirected)		density (edges/ max possible edges)		edge connectivity/ edges (undirected)		fini te diameter/ order		inde pendent set/ order (undirected)		indu ced path/ order (undirected)		radi us/ order (undirected)	
		FW	RAM	FW	RAM	FW	RAM	FW	RAM	FW	RAM	FW	RAM	FW	RAM	FW	RAM
5	ALE 1	0.28	0.29	0.00	0.06	0.44	0.44	0.00	0.01	0.10	0.09	0.33	0.35	0.31	0.32	0.00	0.06
5	GSL 5	0.29	0.30	0.16	0.17	0.60	0.60	0.02	0.02	0.10	0.10	0.29	0.30	0.29	0.27	0.06	0.07
5	LDB 13	0.25	0.27	0.00	0.07	0.35	0.40	0.00	0.02	0.19	0.20	0.50	0.47	0.44	0.47	0.00	0.13
5	LRI 14	0.27	0.27	0.13	0.13	0.37	0.37	0.05	0.05	0.13	0.13	0.40	0.40	0.47	0.47	0.13	0.13
5	NAR 12	0.36	0.36	0.21	0.21	0.46	0.46	0.07	0.07	0.14	0.14	0.36	0.36	0.57	0.57	0.14	0.14
5	PRA 17	0.19	0.19	0.13	0.13	0.40	0.40	0.04	0.04	0.13	0.13	0.44	0.44	0.50	0.50	0.13	0.13
5	PW2 19	0.15	0.38	0.06	0.08	0.32	0.47	0.01	0.03	0.11	0.23	0.32	0.54	0.32	0.38	0.04	0.08
5	SAK 16	0.33	0.32	0.00	0.11	0.60	0.47	0.00	0.02	0.10	0.16	0.26	0.37	0.23	0.42	0.00	0.11
5	SRM 15	0.18	0.19	0.04	0.04	0.24	0.24	0.01	0.01	0.11	0.11	0.50	0.48	0.32	0.33	0.07	0.07
1+	GIR 8	0.29	0.29	0.06	0.06	0.38	0.38	0.02	0.02	0.18	0.18	0.41	0.41	0.47	0.47	0.12	0.12
1+	ICE 9	0.48	0.55	0.04	0.05	0.62	0.63	0.01	0.01	0.09	0.10	0.22	0.25	0.35	0.30	0.09	0.10
1+	KIN 10	0.31	0.31	0.08	0.08	0.42	0.42	0.03	0.03	0.23	0.23	0.46	0.46	0.54	0.54	0.15	0.15
1+	ONT 4	0.23	0.23	0.23	0.23	0.38	0.38	0.10	0.10	0.15	0.15	0.54	0.54	0.46	0.46	0.15	0.15
1+	PW1 18	0.28	0.28	0.11	0.11	0.35	0.35	0.04	0.04	0.17	0.17	0.44	0.44	0.50	0.50	0.11	0.11
1+	VIC 11	0.60	0.50	0.33	0.42	0.75	0.68	0.06	0.11	0.13	0.17	0.33	0.42	0.33	0.42	0.07	0.08
1+	WED 2	0.26	0.27	0.05	0.07	0.29	0.28	0.02	0.03	0.21	0.20	0.47	0.53	0.37	0.40	0.11	0.13
0	AYD 6	0.60	0.60	0.40	0.40	0.71	0.71	0.13	0.13	0.20	0.20	0.40	0.40	0.40	0.40	0.10	0.10
0	GBR 7	0.29	0.50	0.13	0.25	0.49	0.61	0.02	0.18	0.26	0.25	0.29	0.50	0.32	0.38	0.06	0.13
0	KAR 21	0.33	0.33	0.11	0.11	0.39	0.39	0.07	0.07	0.22	0.22	0.44	0.44	0.56	0.56	0.22	0.22
0	TAN 3	0.83	1.00	0.67	0.75	1.07	1.00	0.25	0.50	0.33	0.25	0.33	0.25	0.50	0.50	0.17	0.25
0	WFS 20	0.24	0.50	0.07	0.17	0.49	0.40	0.00	0.17	0.07	0.17	0.22	0.67	0.29	0.50	0.03	0.17



Fig. 2 Map of the world showing geographic locations of all the networks used in the study. Colored dots are shaded according to the number of the five common induced subgraphs in each network.

3.2 Network metrics

Metric values were similar for both food webs and *RAMS* across most networks (Fig. 3). Because metrics were standardized against order or size, there was low variance across the metrics.



Fig. 3 a

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Fig. 3 d IAEES



Fig. 3 e







Fig. 3 g



Fig. 3 h

Fig. 3 a-h Depicts data shown in Table 3. Each panel, a-h, is a different metric calculated on the Food Web (FW in dark gray) and associated *RAM* (light gray) for each network system. Network name abbreviations are listed in Table 1.

3.3 Cluster analysis

The food web network of the West Florida Shelf in the USA was unique to all other food webs (Figs. 4a, 5a). Conversely, the *RAMS* of Weddell Sea in Antarctica, Antarctica and Lake Aydat in France were similar to each other and different from all other *RAMS* (Figs. 4b, 5b).



Fig. 4 a-b PCA biplot of (a) food web and (b) *RAM* networks. The names of all the metrics are abbreviated by the first four letters as appear in **bold** face type in Table 3.

3.4 PCA

Because of the strong influence of size, all metrics were then standardized by size, or order. Preliminary analysis performed on raw data showed that the first PC was largely explained by size in both food webs (>90%) and *RAMS* (>55%). Using standardized data (Table 3), clique number became the most influential metric. The first principal component explained 70% of the variance (Fig. 5).

There were a few outlier networks, primarily Burundi Lake in Tanganyika. Lake Aydat in France and Lake Victoria in Kenya are strongly influenced by this first principal component. Marine food webs tend to group more closely together than freshwater systems (Fig. 6).



Fig. 5 b

Fig. 5 a-b Principal components of (a) food web and (b) RAM networks. See Table 1 for key of numeric labels of networks.







Fig. 6 b

Fig. 6 a-b Dendrogram resulting from cluster analysis of (a) food web and (b) *RAM* networks. A unique color is assigned to each group of nodes within the dendrogram whose linkage is less than 70% of the maximum linkage. X-axis: the numeric network abbreviations specified in Table 1. Y-axis: distance between two networks being connected.

4 Discussion

A goal of this study was to determine similarities in structure among food webs that are otherwise disparate with regard to species, population, and size. Through this study, we determined not only that there were pairs of network systems that were highly similar in structure, once appropriately normalized for size and makeup, but also that a majority of food webs have similar structural components when compared with random food webs. Structural similarities have been identified in sub components within food webs (Stouffer et al., 2007).

Other studies have also demonstrated that food webs from different types of ecosystems (i.e. marine, estuarine, fresh-water, terrestrial) share fundamental structural and ordering characteristics, despite variable diversity and complexity inherent in the web (Camacho et al., 2002; Dunne et al., 2004).

Based on the cluster analysis, environmental and geographical characteristics have little to do with how food webs are related to each other. There are no apparent environmental or geographical distinctions that easily explain why the West Florida Shelf, USA system was unique from all other systems or why the Weddell Sea, Antarctica and Lake Aydat, France cluster separately from all other systems. Most likely, West Florida Shelf system stands out from other systems because of the original motivation for creating the model. The modelers wanted to investigate the effect of phytoplankton shading on benthic primary production. This research question is quite different than that motivating any of the other study system (Table 2). Therefore, the uniqueness of ecosystems may be attributed to the research question structuring the model, rather than the inherent organization or structure of the ecosystem itself.

We attempted to control for some of the variability, inherent model construction for different research purposes and goals, by removing circuits and reducing full food webs into RAMS. Several other studies that examined food webs for similar network structures only considered substructures on full food webs (Borrelli, 2015; Stouffer et al., 2007). Despite our attempt to normalize models against initial construction biases, it is possible that RAMS still capture some of these model construction biases. For example, if food web A has one group called 'planktivorous fish' preying on zooplankton compared to food web B having three groups called 'herring' and 'mackerel' and 'sandlance' all preying on zooplankton, then those two webs could look different after reducing them to RAMS. How modelers aggregate groups of species does impact network ecology and graph theory metrics. Modelers often make their decision on how to group species based on a particular research focus (Table 2). In this study, we used all Ecopath derived models and it is a common practice that Ecopath modelers aggregate species into functional groups, based on available data, in order to limit the number of nodes and produce a manageable sized network (Christensen et al., 2008). We found a high degree of aggregation, where most models contained a high percentage of nodes that included several functionally similar species, as opposed to a single species (Table 2). It is suggested that the optimal number of nodes, 12-24, above and below which mass balance food web models become less helpful for understanding these complex systems (Christensen et al., 2008; Plagányi, 2004; Plagányi, 2007). In this study, we then further aggregate species across trophic levels by removing cycling to reduce SCCs to a single node (Allesina et al., 2005) (Table 2). These types of aggregation methods have the similar objective of reducing complexity. Furthermore, PCA and cluster analyses results are very similar for FW and RAMS which is justification for creating RAMS in the first place.

Alesina et al. (2005) only found four out of 17 food webs that did not reduce to a single node after a process similar to our *RAM* construction. Allesina et al. (2005) uses the term DAGs – Directed Acyclic Graphs to describe the same thing as our *RAMS*. The term DAG describes a particular type of mathematical object that implies an abstract mathematical structure whereas we feel the term *RAM* more clearly represents the object itself. We discovered that the food webs in our data set also had high cyclicity before removing detritus. Once the nodes associated with detritus were removed from our food webs, we found many more "interesting" reduced graphs.

This study further emphasizes that food webs are not random and that they are more similar across a range of ecosystem types than may be predicted. The similarities we were able to identify were embedded in the graphical structure of the network and are not necessarily connected to obvious environmental or geographical properties of the ecosystems themselves. These findings emphasize the importance of using innovative techniques for investigating and quantifying complex networks for the purpose of ecosystem management.

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